Maxima and minima: I
Based on lecture notes by James McKernan
Recall that $K \subset \mathbb{R}^{n}$ is closed if the complement is open. Recall also that this is equivalent to saying that $K$ contains all of its limit points.

Blackboard 1. We that $K \subset \mathbb{R}^{n}$ is bounded if there is a real number $M$ such that

$$
\|x\| \leq M
$$

for all $x \in K$.
We say that $K$ is compact if $K$ is closed and bounded.
Note that $K$ is bounded if and only if

$$
K \subset B_{M}(O)
$$

where $O$ is the origin.

## Example 2.

(1) $[a, b] \subset \mathbb{R}$ is compact.
(2) $(a, b] \subset \mathbb{R}$ is bounded but not closed (whence not compact).
(3) $[a, \infty) \subset \mathbb{R}$ is closed but not bounded (whence not compact).

$$
\begin{equation*}
K=\left\{x \in \mathbb{R}^{n} \mid\|x\| \leq M\right\} \tag{4}
\end{equation*}
$$

is compact.

$$
\begin{equation*}
K=\left\{x \in \mathbb{R}^{n} \mid\|x\|<M\right\} \tag{5}
\end{equation*}
$$

is bounded but not closed.
Theorem 3. Let $f: K \longrightarrow \mathbb{R}$ be a continuous function.
If $K$ is compact then there are two points $\vec{a}_{\min }$ and $\vec{a}_{\max }$ in $K$ such that

$$
f\left(\vec{a}_{\min }\right) \leq f(\vec{x}) \leq f\left(\vec{a}_{\max }\right)
$$

The proof of (3) is highly non-trivial.
Blackboard 4. Let $K \subset \mathbb{R}^{n}$. We say that $\vec{a} \in K$ is an interior point if there is an open ball containing $\vec{a}$ which is contained in $K$.

Otherwise $\vec{a}$ is a boundary point of $K$.
Example 5. If $K=[a, b] \subset \mathbb{R}$ then every point $a<x<b$ is an interior point and $a$ and $b$ are boundary points.

To find the maxima and minima of $f: K \longrightarrow \mathbb{R}$ we break the problem into two pieces:
I. The interior points. Use the derivative test, this lecture.
II. The boundary points. Use Lagrange multipliers, see lecture 21.

Notice that the boundary can have a rather complicated structure in higher dimensions. For example, in $\mathbb{R}^{3}$ the closed unit ball is compact. The interior is the set of points in the open unit ball and the set of boundary points is the set of points on the unit sphere.

Blackboard 6. Let $f: K \longrightarrow \mathbb{R}$ be a function and let $\vec{a} \in K$ be an interior point. We say that $f$ has a local minimum at $\vec{a}$ if there is an open ball $U=B_{\delta}(\vec{a})$ centred at $\vec{a}$ contained in $K$ such that

$$
f(\vec{a}) \leq f(\vec{x})
$$

for all $\vec{x} \in U$.
We can define local maxima in a similar fashion.
Blackboard 7. Let $f: K \longrightarrow \mathbb{R}$ be a differentiable function. We say that a point $\vec{a} \in K$ in the interior of $K$ is a critical point if $D f(\vec{a})=\overrightarrow{0}$.

Proposition 8. Let $K \subset \mathbb{R}^{n}$ be a compact set and let $f: K \longrightarrow \mathbb{R}$ be a differentiable function. Let $\vec{a} \in K$ be an interior point.

If $\vec{a}$ is a local maximum, then $\vec{a}$ is a critical point.
Proof.

$$
\begin{aligned}
\frac{\partial f}{\partial x_{i}}(\vec{a}) & =\lim _{h \downarrow 0} \frac{f\left(\vec{a}+h \hat{e}_{i}\right)-f\left(\hat{e}_{i}\right)}{h} \leq 0 \\
\frac{\partial f}{\partial x_{i}}(\vec{a}) & =\lim _{h \uparrow 0} \frac{f\left(\vec{a}+h \hat{e}_{i}\right)-f\left(\hat{e}_{i}\right)}{h} \geq 0 .
\end{aligned}
$$

Recall the one variable second derivative test.
Theorem 9. Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be of class $\mathcal{C}^{2}$.
(i) If $f^{\prime}(a)=0$ and $f^{\prime \prime}(a)<0$, then $a$ is a local maximum of $f$.
(ii) If $f^{\prime}(a)=0$ and $f^{\prime \prime}(a)>0$, then $a$ is a local minimum of $f$.

If $f^{\prime}(a)=0$ and $f^{\prime \prime}(a)=0$, then we don't know.
Proof of (i). Since $f$ is of class $\mathcal{C}^{2}$ then $f^{\prime \prime}$ is continuous. Hence $f^{\prime \prime}$ is positive in some small enough neighborhood of $a,(a-\epsilon, a+\epsilon)$. Let $b \in(a-\epsilon, a+\epsilon)$. Then by Taylor's Theorem with remainder

$$
f(b)=f(a)+f^{\prime}(a)(b-a)+\frac{1}{2} f^{\prime \prime}(\xi)(b-a)^{2},
$$

for some $\xi \in(a, b)$. But then $\xi \in(a-\epsilon, a+\epsilon)$, and so $f^{\prime \prime}(\xi)<0$. Since $f^{\prime}(a)=0$ we have that

$$
f(b)=f(a)+\frac{1}{2} f^{\prime \prime}(\xi)(b-a)^{2}>f(a) .
$$

To figure out the multi-variable form of the second derivative test, we need to consider the multi-variable second Taylor polynomial:

$$
P_{\vec{a}, 2} f(\vec{x})=f(\vec{a})+\nabla f(\vec{a}) \cdot \vec{h}+\frac{1}{2} \vec{h}^{t} H f(\vec{a}) \vec{h} .
$$

where $\vec{h}=\vec{x}-\vec{a}$ is a column vector and $h^{t}$ is the same row vector. Recall that

$$
H f(\vec{a})=\left(\frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(\vec{a})\right)
$$

The important term is then

$$
Q(\vec{h})=h^{t} H f(\vec{a}) h .
$$

Blackboard 10. If $A$ is a symmetric $n \times n$ matrix, then the function

$$
Q(\vec{x})=\vec{x}^{t} A \vec{x}
$$

is called a symmetric quadratic form. Note that $Q(\overrightarrow{0})=0$.
We say that $Q$ is positive definite if $\vec{x} \neq \overrightarrow{0}$ implies that $Q(\vec{x})>0$.
We say that $Q$ is negative definite if $\vec{x} \neq \overrightarrow{0}$ implies that $Q(\vec{x})<0$.
Example 11. If $A=I_{2}$ then

$$
Q(x, y)=(x, y)\left(\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right)\binom{x}{y}=x^{2}+y^{2}
$$

which is positive definite. If $A=-I_{2}$ then $Q(x, y)=-x^{2}-y^{2}$ is negative definite. Finally if

$$
\left(\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right)
$$

then $Q(x, y)=x^{2}-y^{2}$ is neither positive nor negative definite.
Proposition 12. If $\vec{a} \in K \subset \mathbb{R}^{n}$ is an interior point and $f: K \longrightarrow \mathbb{R}$ is $\mathcal{C}^{3}$, $\vec{a}$ is a critical point and $Q(\vec{h})=\vec{h}^{t} H f(\vec{a}) \vec{h}$, then
(1) If $Q$ is positive definite, then $\vec{a}$ is a minimum.
(2) If $Q$ is negative definite, then $\vec{a}$ is a maximum.
(3) If the determinant of $\operatorname{Hf(\vec {a})}$ is not zero and $Q$ is neither positive nor negative definite, then $\vec{a}$ is a saddle point.

Proof. Immediate from Taylor's Theorem.
Proposition 13. If $A$ is a $n \times n$ matrix, then let $d_{i}$ be the determinant of the upper left $i \times i$ submatrix. Let $Q(\vec{h})=h^{t} A h$.
(1) If $d_{i}>0$ for all $i$, then $Q$ is positive definite.
(2) If $d_{i}>0$ for $i$ even and $d_{i}<0$ for $i$ odd, then $Q$ is negative definite.

Let's consider the $2 \times 2$ case.

$$
A=\left(\begin{array}{ll}
a & b \\
b & d
\end{array}\right)
$$

In this case

$$
Q(x, y)=a x^{2}+2 b x y+c y^{2} .
$$

Assume that $d_{1}=a>0$. Let's complete the square. $a=\alpha^{2}$, some $\alpha>0$.

$$
Q(x, y)=(\alpha x+b / \alpha y)^{2}+\left(d-b^{2} / \alpha^{2}\right) y^{2}=(\alpha x+b / \alpha y)^{2}+\left(a d-b^{2}\right) / a y^{2}
$$

In this case $d_{1}=a>0$ and $d_{2}=a d-b^{2}$. So the coefficient of $y^{2}$ is positive if $d_{2}>0$ and negative if $d_{2}<0$.

